

*Sub 2*  
a solenoid connected directly to the valve to move the valve between the first and second positions independent of the lever in response to an electrical input to the solenoid.

*22/2* The assembly of claim *21*, further including a lock engaging the lever to lock the lever in a position having the valve in the second position.

*23/3* The assembly of claim *22* wherein the lock includes a lock solenoid and a lock bar coupled to the lock solenoid, the lock bar engaging the lever, and the lock solenoid being operable to move the lock bar in response to an electrical input to the lock solenoid.

*24/4* The assembly of claim *22* wherein the lock includes a lock bar movable into and out of engagement with the lever and a lock solenoid coupled to the lock bar, the lock solenoid being operable to move the lock bar relative to the lever.

*25/5* The assembly of claim *21* wherein the lever is pivotally coupled to the manifold.

*26/6* The assembly of claim *21* wherein the solenoid is positioned between the manifold and the lever.

*27/7* The assembly of claim *21* wherein the valve includes a stem, the lever includes an opening, and a part of the stem is received in the opening.

*28/8* A controller for a hospital bed having a frame and a support section vertically movable relative to the frame for supporting a patient, the controller including:

a cylinder having a housing and a piston for moving the support section relative to the frame;

a supply path providing fluid communication between a fluid supply and the cylinder;

a supply valve in the supply path operated by a first solenoid for selectively interrupting the fluid communication through the supply path, the supply valve having a manual override;

an electrical supply actuator connected to the first solenoid to electrically actuate the first solenoid to control the interruption of the fluid communication through the supply path; and

a manual actuator connected to the manual override to manually control the interruption of the fluid communication through the supply path, the manual actuator having a

first setting wherein the fluid communication is uninterrupted and a second setting wherein the fluid communication is interrupted.

29/8. The controller of claim 8 further including an electrically actuated setting remover coupled to the electrical supply actuator to remove a setting of the manual actuator upon electrical actuation of the first solenoid.

30/10. The controller of claim 8 further including a return path providing fluid communication between the fluid supply and the cylinder, a return valve operated by a return solenoid for selectively interrupting the fluid communication through the return path, the return valve having a manual override, and an electrical control including the electrical supply actuator and an electrical return actuator connected to the return solenoid to control the interruption of the fluid communication through the return path, wherein the manual actuator is connected to the return valve manual override to manually control the interruption of the fluid communication through the return path.

31/11. A valve assembly for a hospital bed, including:  
a supply member having an interrupt position interrupting a supply path providing fluid to a device for positioning the bed;  
a return member having an interrupt position interrupting a return path returning fluid from the positioning device;  
a first actuator to position the supply and return members, the first actuator having a supply state wherein the return member is in the interrupt position, a return state wherein the supply member is in the interrupt position, and a neutral state wherein the first actuator does not position the supply and return members;  
a second actuator to position the supply and return members into and out of their respective interrupt positions;  
a controller that generates an override signal when the second actuator is actuated; and  
an override device that responds to the override signal by placing the first actuator in the neutral state.

32/12. The assembly of claim 31 wherein the first actuator is a multi-state manual actuator.

33/13. The assembly of claim 32 wherein the second actuator is an electrical actuator.